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A satellite remote-sensing multi-index approach to discriminate pelagic Sargassum in the waters of the Yucatan Peninsula, Mexico

25 Abstract

26 Recently, the need for quantitative information on the spatiotemporal distribution of 27 floating macroalgae, particularly Sargassum spp., has grown because of blooms of these 28 species in the Gulf of Mexico and Caribbean Sea. Remote sensing is one of the most 29 frequently used tools to assess pelagic Sargassum distribution. The purpose of this study 30 was to implement a methodological approach to detect floating algae in an efficient and 31 replicable manner at a moderate cost. We analyzed Landsat 8 imagery, from which we 32 calculated four vegetation indices and one floating-algae index to implement a supervised 33 classification, together with the bands 2 and 5, using the Random Forest algorithm. The 34 analysis was performed monthly from 2014 to 2015 for the northeastern Yucatan Peninsula, 35 Mexico, with a total of 91 analyzed images. The quantitative performance metrics of the 36 classifier (overall, Kappa and Tau) were greater than 80%, whereas bands 2 and 5 as well as 37 atmospherically resistant vegetation index made the greatest contributions to the 38 classifications. During summer 2015, more than 4,000 ha of Sargassum coverage per image 39 were observed, which was substantially greater than that over the rest of the period. This 40 approach constitutes a transferable alternative for the systematic detection of Sargassum, 41 which enables a quantitative semi-automated time series comparison.

42 Keywords: *Sargassum*, macroalgae, Landsat, Random Forest, remote sensing

43 Introduction

The pelagic *Sargassum* genus include two species (from now on abbreviated as *spp.*, as it is referred to abbreviate more than one unspecified species) of Phaeophyta macroalgae that are irregularly distributed in configurations whose lengths range from 50 cm to several kilometres (Butler et al. 1983). *Sargassum* is widely distributed along the Gulf of Mexico and the Caribbean Sea, where biological assemblages of high economic and ecological value to Mexico, the United States, and Cuba are found (Thiel and Gutow 2005).

The marine communities composed of Sargassum and its occupants are part of intricate 50 51 trophic chains and host different commercial fish species during their early stages of 52 development, e.g., Coryphaena, Abudefduf, and Caranx (South Atlantic Fishery Management 53 Council 2002; Vandendriessche et al. 2007), as well as endangered species and other species of 54 high ecological value, such as sea turtles and pelagic seabirds (Mansfield and Putman 2003; 55 Moser and Lee 2012; Witherington, Hirama, and Hardy 2012). 56 Although Sargassum represents important ecological and economic interests, the 57 anomalous and excessive growth of this macroalga has been recorded in the Gulf of Mexico, the 58 Caribbean Sea, and the Western Central Atlantic (WCA) since 2006 (Gower et al. 2006; Gower 59 and King 2008; Gower and King 2011; Gower, Young, and King 2013; Wang and Hu 2016). 60 This excessive growth has generated massive off-shore *Sargassum* shoals that negatively affect 61 coastal towns, especially the tourism and service sectors as well as certain coastal ecosystems and 62 endangered species (Smetacek and Zingone 2013; Gavio, Rincón-Díaz, and Santos-Marín 2015; 63 Maurer, De-Neef, and Stapleton 2015; Schell, Goodwin, and Siuda 2015; van-Tussenbroek et al. 64 2017). 65 The first studies of *Sargassum* communities were conducted from oceanographic cruises

in the Atlantic Ocean (Stoner 1983; Huffard et al. 2014). As a technological alternative, remote
sensing has been used as a major tool in studies of *Sargassum* worldwide, including its detection
at the surface of the water and on the sea bed (less than 10 m in depth) (Hu, Hardy, and Hocberg
2015; McCarthy 2016; Wang and Hu 2016, Xing et al. 2017).

The initial studies that employed remote sensing techniques used low spatial resolution
multispectral imaging sensors with high temporal resolution to assess algae blooms in the Yellow
Sea (Hu 2009), the Gulf of Mexico (Gower and King 2011), the northern region of the Gulf of

Mexico (specifically, the area affected by the 2010 oil spill) (Hu, Hardy, and Hochberg 2015; Hu
et al. 2016), and the WCA (Wang and Hu, 2016)

In this context, it is important to understand the spatial-temporal dynamics of floating *Sargassum* lines to design and implement strategies to address anomalous events as well as to advance our understanding of their origins, under which physical and biological conditions they occur, and the amount of *Sargassum* expected on the beach, among other aspects.

In the Gulf of Mexico and the Lesser Antilles, formal initiatives have been aimed at providing near real-time information on the distribution patterns of pelagic *Sargassum* using Moderate Resolution Imaging Spectroradiometer (MODIS) data with long term and detailed temporal coverage (Optical Oceanography Laboratory, University of South Florida). With regard to the north of the Gulf of Mexico in particular, one initiative uses medium resolution satellite images (Landsat) (Webster and Linton 2013) to provide semi-quantitative information products to assess and quantify spatial and temporal patterns.

In Mexico, specifically in Quintana Roo (Mexican Caribbean), different strategies have
been implemented to address this issue. However, baseline data on the spatial-temporal patterns
and dynamics of this macroalgae in adjacent waters are lacking.

The objective of this study was to expand existing methodological approaches through the implementation of a low cost and replicable approach with a relatively low computing demand to detect and monitor pelagic *Sargassum* in the waters of the Yucatan Peninsula, Mexico. This study will enable the analysis of spatial-temporal dynamics of pelagic *Sargassum* to inform natural resource managers as well as planners to act in case of contingencies.

In the next sections, we present a methodological approach for the detection and
assessment of *Sargassum* in a quantitative, robust, and semi-automated manner along with an
evaluation of its accuracy.

97 Materials and Methods

98 Study area

99 For this study, we selected the northeastern region of the Yucatan Peninsula, Mexico because it is 100 the major entry point of water into the Gulf of Mexico. This region is known for the Cabo 101 Catoche seasonal upwelling and is characterized by strong sea currents as well as associated 102 biological and ecological processes (Merino 1997; Sheinbaum et al. 2002; Schmitz et al. 2005; 103 Rousset and Beal 2010). In addition, the area is located to the north of the beaches in the state of 104 Quintana Roo, Mexico (van Tussenbroek et al. 2017), where large Sargassum shoals were 105 recorded in 2014 and 2015 (Figure 1). As Hu et al. (2016) recognized, knowledge about the 106 abundance of *Sargassum* in the eastern region of the Gulf of Mexico is limited; therefore, 107 studying the *Sargassum* of that region is strategic for generating information about this

108 macroalga.

109 Image selection and preprocessing

110 Given the size of the Sargassum lines reported in this area, which MODIS or the Medium 111 Resolution Imaging Spectrometer (MERIS) cannot detect, and considering the advances achieved 112 by similar studies using Landsat (Hardy 2014; Hu et al. 2016), we used Landsat 8 (L8) 113 Operational Land Imager (OLI) images with a 30 m spatial resolution. We selected four scenes 114 for the images covering the area of interest (paths 018 and 019 as well as rows 044 and 045), took 115 the first image acquired each month for the four scenes along the studied period, and built a set of 116 91 L8 images for the years 2014 and 2015 (five images were missed from the source archive at 117 the time of this search in July 2016).

118 During this period of time, a *Sargassum* bloom was reported in the Caribbean (Maurer, 119 De-NEef & Stapleton, 2015; Azanza-Ricardo and Pérez-Martín, 2016). Therefore, by selecting 120 this time frame, we ensured that *Sargassum* would be present in at least some of the images, 121 thereby allowing the implementation of this approach and the spatial-temporal assessment of the 122 massive bloom of the macroalga along the coasts of the Mexican Caribbean. 123 Satellite images were downloaded from the United States Geological Survey (USGS, 124 2016), and all were subject to an atmospheric correction (see Hu, 2004 and GRASS Development 125 Team, 2017). 126 A land mask was applied to each image based on the Global Administrative Area

polygons (Hijmans et al. 2016). Pixels whose configuration in the quality band (QB) indicated
the presence of clouds, cirrus, snow, and ice were masked so that only the pixels whose QB
configuration indicated possible water and unaffected pixels remained active (USGS, 2014).

130 Vegetation indices

After a literature review (and given the basic recommendations by Hu, Hardy, and Hochberg,
2015), a set of five vegetation indices with the potential to contribute to *Sargassum* detection was
defined: Normalized difference vegetation index (NDVI), Atmospherically resistant vegetation
index (ARVI), Soil-adjusted vegetation index (SAVI), Enhanced vegetation index (EVI) and
Floating algae index (FAI) (Equations (1)-(6) in Table 1).
To make these calculations using the L8 images, we used band 2 (0.452 – 0.512 µm) as
Blue (B), band 4 (0.636 – 0.673 µm) as Red (R), band 5 (0.851 – 0.879 µm) as Near InfraRed

- $157 \qquad \text{Diac} (D), \text{ cand } (0.000 \text{ or } 0.070 \text{ pm}) \text{ as real (10), cand c (0.001 \text{ or } 0.075 \text{ pm}) as real minutes}$
- 138 (NIR), band 6 (1.566 1.651 μ m) as Short Wave InfraRed (SWIR) (Table 1).

139 Supervised image classification

140 For each image, a classification model was generated based on the selected training sites using a 141 Random Forest algorithm (Liaw and Wiener 2002). This classifier consists of a combination of 142 classification trees, in which each one is generated from a set of random sites independently 143 sampled from the entry set, and each tree casts a single vote for the most popular type of entry 144 vector (Breiman 1999; Pal 2005). This machine learning algorithm is regarded as one of the most 145 efficient algorithms in terms of prediction accuracy, speed, and efficiency for large databases. 146 Although the individual contribution of each index is combined during the classification, in terms 147 of detecting *Sargassum* aggregations, we assumed that the multiple criteria that this algorithm are given with the different indices is an advantage. Furthermore, the algorithm is also well 148 149 recognized because it offers an intuitive approach to assess the importance of each independent 150 variable used in the model (Crisci, Ghattas, and Perera 2012). 151 Different remote sensing studies have used Random Forest because it provides greater 152 accuracy than other machine learning algorithms (Akar and Güngör 2012). In this regard, 153 Random Forest has been used for acoustic data (Lucieer et al. 2012), to map marsh vegetation 154 (van Beijma, Comber, and Lamb 2014), and even as a prediction model for harmful algal blooms 155 (Kehoe et al. 2012), among other applications. This commercial algorithm is accessible to any 156 person interested in detecting floating Sargassum; hence, the replicability of this method is 157 ensured. 158 The classification inputs were the five vegetation indices obtained, i.e., NDVI, ARVI, 159 SAVI, EVI and FAI, combined with bands 2 (blue, 0.452 - 0.512 µm) and 5 (SWIR, 0.851 -

 $160 \quad 0.879 \,\mu\text{m}$). All of the data contributed by the indices individually and as a set as well as

161 additional information derived from the contrast between the NIR and the blue bands were used

to distinguish floating algae (Hu 2009, Xing et al. 2017). For the classification parametrization,
we set the number of variables in the random subset at each node (*m*) as 3, and the number of
trees in the forest (*k*) as 1,000, with replacement of samples at each step.

To provide the classifier with a wider spectral context of the analyzed image, we included training sites for the other objects present in the scene; hence, we expected the classifier to have more chances of correctly classify *Sargassum*. Hence, sets of training sites were visually defined (polygons in vector format) for the classes of *Sargassum*, clouds, blue sea (open sea), sea with sun glint, and cloud shadows (shadows) based on the different composites from the generated indices (three at a time, one for each channel) and a false color composite (bands 5,2,1) of the images.

We obtained between 38 and 123 training sites (polygons) per image (mean 69), where 33.0% of them were labeled *Sargassum*. The latter training sites varied from four to 100 pixels in size depending on the cover extension of the *Sargassum* in each image. The rest of the classes were trained with a maximum of 250 pixels each.

With these training sites, we expected to capture the spectral variation in the classes within each assessed individual image, considering the influence on the image that different data acquisition conditions had (solar light angle of incidence, sensor angle, and even the presence of mist) (Wang and Hu 2016). Bands 5 and 2 as well as the index values were extracted from these polygons for their corresponding images.

181 The original individual classifications with five categories were reclassified to contain 182 only the *Sargassum* class, which was subsequently converted into polygons in vector format so 183 that the rest of the classes were omitted. In addition, rasters were generated with the probability 184 of each pixel of being *Sargassum*. We also obtained values of the general errors in the

classification determined via cross validation as well as scores of the importance of the variables
to the general classification and for the *Sargassum* class exclusively.

187 A graphical assessment of the importance values for the five indices and bands under
188 consideration was conducted to determine the main decision tree criteria for the five classes,

189 particularly for the *Sargassum* class.

190 Supervision and quantification of Sargassum

191 As part of the supervision process, the polygons identified as *Sargassum* were subjected to visual 192 quality control based on the visual compositions used before (i.e., the indices and bands). During 193 the supervision process, errors of commission were corrected by the operator; however, omission 194 errors were not corrected, primarily because of the significant manual digitization effort that this 195 procedure entails. The *Sargassum* polygons obtained after this visual supervision were 196 considered the final detection in each image. 197 The Sargassum probability (i.e., a raster of probabilities derived from the classification) 198 was analyzed, both in the original classification and in the final detection to determine the range

199 of probability values over which greater intervention was required to correct errors of

200 commission.

201 The quantification is reported as hectares of *Sargassum* detected for each month and year.

202 Sargassum classification accuracy

A quantitative validation of the final *Sargassum* polygons was performed. Based on the analysis of the probability of each polygon being *Sargassum*, the probability quartiles were defined as tiers in the distribution of the verification sites in a uniform, stratified scheme. A total of 120 verification points per image were defined (i.e., 30 points per probability quartile), and the

207 verification points were randomly distributed among the pixels in each quartile.

208	The validation design included only the classified images with detected Sargassum. If no
209	Sargassum was observed within a scene, then it was excluded from the validation. A person
210	external to the supervision of the classification categorized the validation points (in vector
211	format) using the composites of false color indices with the bands 5, 2, and 1 as a reference. The
212	points were labeled Sargassum or non Sargassum, and both the probabilities of Sargassum class
213	and the final classification were invisible to the person who performed the validation.
214	A confusion matrix was generated from the polygons obtained from the final
215	classification (<i>Sargassum</i> or <i>non Sargassum</i>), and the class assigned to the verification (a = true
216	positives, $b = false$ positives, $c = false$ negatives and $d = true$ negatives) (Green et al. 2000;
217	Anderson, Lew, and Peterson 2003).
218	In addition, the quantitative measures of the intrinsic performance of the classifier were
219	calculated (overall, omission error, and commission index) (Anderson et al. 2003) as were the

220 Kappa and Tau accuracy metrics (Green et al. 2000; see Equations (7)-(11) in Table 2).

221 **Results**

222 Maps of the monthly distribution and coverage of pelagic *Sargassum* were generated for the

223 northeast Yucatan Peninsula using the above described semi-automated detection protocol and

Landsat 8 OLI images for 2014 and 2015.

225 Image analysis

- 226 Of the 91 analyzed images, 54 (60.0%) showed evidence of *Sargassum*; thus, they were
- 227 classified. Likewise, 31 (34.0%) did not show evidence of the presence of *Sargassum*, whereas
- the remaining six (6.0%) exhibited high cloud coverage (> 80.0%), making detection impossible.

A gap of five images exited for the studied area and period that were not available in the USGSarchive.

231	Bands 2 and 5 along with the ARVI had the greatest importance, on average, in the
232	decision making of the classification trees (Figure $2(a)$). Importantly, this participation is relative
233	to all classes considered in the classification of each image and that their variability range was
234	wide with an interquartile range (50.0% of the data) that overlapped with the inputs from the rest
235	of the indices. On the other hand, when we only considered the Sargassum class, NDVI and
236	SAVI were the indices with the greatest importance (Figure $2(b)$).
237	The average global classification accuracy value derived from the cross validation as part
238	of the Random Forest classification process was 97.7% ($\pm 2.2\%$).
239	The supervision of the direct result of the classification resulted in the elimination of
240	polygons erroneously labeled Sargassum in 60.0% of the classified images. This circumstance

241 occurred most frequently in cloud edges and cloud shadows.

242 Distribution of the Sargassum probability values

In general, for the distribution of the *Sargassum* assignment probability values in a complete scene, we noted that a great proportion of the set of pixels in the image corresponded to low or null probabilities. A large proportion of pixels also showed a 0.1 to 10.0% probability of being *Sargassum*, and only a few of these were finally classified as such. In contrast, we found pixels with a high probability of being *Sargassum* (> 90.0%) but that also showed greater probabilities of being other classes; hence, these pixels were not classified as *Sargassum*.

Most errors of commission detected in the supervision after classification were found in the group of pixels with a *Sargassum* assignment probability between 10.0% and 80.0%. When assessing the distribution of the probability values to be assigned as *Sargassum* in the polygons

removed during supervision, we observed that the highest percentage of changes (after the elimination of the errors of commission) occurred in pixels with *Sargassum* probability values between 10.0% and 70.0%; thus, a greater confusion was accompanied by a lower assignment probability. However, most pixels with a high probability of being *Sargassum* (> 80.0%) were maintained as such after supervision; thus, few errors of commission occurred at those probability levels.

In terms of the distribution of the *Sargassum* probability values of the pixels that effectively remained as such (distributed in light gray in Figure 3(*a*)), 50.0% of the pixels presented classification probability values between 65.0% and 100.0%.

Figure 3(*b*) shows the effect of removing the polygons wrongly classified as *Sargassum*; the average of probabilities increased, and the interquartile range decreased. Furthermore, 50.0% of the data were distributed between 77.0% and 98.0% probabilities of being classified as *Sargassum*. This pattern was consistent for all of the classified scenes, and the highest incidence of refinement was found in pixels with medium probability values, which also increased the centrality of the probability of the pixels correctly classified as *Sargassum*.

267 Quantification of Sargassum

268 The temporal distribution pattern of *Sargassum* in the area differed for 2014 and 2015. In 2015,

269 Sargassum coverage was four times larger than that in 2014, which is quantitative evidence of its

270 massive growth in this region (Figures 4 and 5).

271 In 2014, *Sargassum* drifts were scattered throughout the study area with higher

- 272 concentrations along the continental slope. In 2015, the aggregation of large amounts of
- 273 Sargassum was evident, and it followed the pattern of surface flows, particularly along the edge

of the continental shelf. On the continental shelf, the presence of *Sargassum* was minimal in 2014
but was significant in 2015.

276 In 2014, two periods of greater *Sargassum* coverage were recorded; the first occurred in 277 August, and the second occurred in November and December with values ranging from 1,000 to 278 4,000 ha for each event, respectively. In 2015, the first evidence of floating Sargassum 279 aggregations of approximately 1,000 ha in size were observed in March; later that year, however, 280 the maximum macroalga accumulations were recorded as more than 6,000 ha of Sargassum 281 detected during July and August (Figure 5). During September and October of that same year, the 282 amount of *Sargassum* decreased considerably with a coverage of less than 1,000 ha. 283 During the periods of maximum *Sargassum* aggregation (November and December 2014) 284 as well as in July and August 2015, the paths along which the maximum values were detected 285 diverged. The maximum values were first found in path 18 and later in path 19, suggesting a 286 response to the direction of the surface currents in the area. 287 Regarding the temporal differences in *Sargassum* coverage between months, sudden 288 changes were noted from November 2014 to January 2015 and from July to September 2015, 289 during which the differences in the area of *Sargassum* coverage between months was greater 290 (Figure 5).

Of the *Sargassum* coverage values detected in 2014 and 2015, increases between 50.0% (August 2014) and up to 400.0% (June-July 2015) were recorded for a single scene, providing evidence about the anomalous nature of the event recorded in 2015.

294 Sargassum classification accuracy

Based on the confusion matrix for the 2,040 assessed validation points, different metrics wereestimated to judge the efficiency of the proposed approach to detect floating algae with L8

images (Table 3).

The global performance value of the classification was 93.4%, which includes the errors of omission and commission. The rate of omission or false negatives was 19.0%. Thus, the percentage of detected *Sargassum* was underestimated by the classifier (Table 2). Finally, the rate of errors of commission, or false positives, was 2.7%.

The classification accuracy metrics showed values greater than 80.0%, which represents a satisfactory level of performance using the methodological approach presented here. With a Kappa value of 81.2%, it is assumed that the classification process avoided this percentage of errors relative to the errors that a completely random classification would have generated. In addition, the Tau value indicates that 97.5% more pixels were correctly classified than the result expected from a random classification. These accuracy metric values support the calculated *Sargassum* coverage estimates.

309 **Discussion**

Based on the available literature and to the best of our knowledge, this study is the first to assess *Sargassum* via remote sensing using an integrated multi index approach as well as the first to
document the 2015 *Sargassum* bloom along the Yucatan Peninsula.

313 Quantification of Sargassum in waters of the Yucatan Peninsula

The major increases in *Sargassum* coverage over the study area were recorded during autumnwinter 2014 and summer 2015. For the greater part of 2014, no large *Sargassum* aggregations were detected, but from August to December of that year, a considerable increase in coverage was recorded. Wang and Hu (2016) reported the same pattern for the WCA, and an increase in *Sargassum* coverage was noted again in the first quarter of 2015. The months of the greatest 320 with the same period reported for the WCA, with remnants recorded until November of that year. 321 The temporal coincidence of the greater Sargassum coverage values in our study area and 322 the WCA suggests that these *Sargassum* lines in the Mexican Caribbean did not originate in 323 southern regions of the Caribbean Sea because blooming apparently occurred at the same time. In 324 contrast, the bloom might have originated closer to our study region, with the peculiarity that the 325 coverage of *Sargassum* in the assessed paths showed a time lag. Specifically, the eastern path 326 ranked first in terms of the increase in coverage, followed by the neighboring path to the west, 327 which followed the direction of the surface currents and the prevailing winds (i.e., from east to 328 west; Enríquez, Mariño-Tapia, and Herrera-Silveira 2010; Reyes-Mendoza et al. 2016).

Sargassum presence in our study area were from June to September of 2015, which coincided

Regarding of the use of Landsat imagery to detect *Sargassum* coverage, we related our results to those of Hu et al. (2016); although our study differs in the years analyzed, it was the only study that used the same input data until today. They detected *Sargassum* in the area affected by the Deep-Water Horizon oil spill of 2010 in the northern region of the Gulf of Mexico, and they reported a coverage of thousands of hectares for the first trimester of the year. This order of magnitude of *Sargassum* coverage is consistent with our results.

335 Accuracy of Sargassum detection

319

Importantly, a significant percentage of actual floating *Sargassum* corresponds to patches of minimal size, which are difficult to detect via remote sensing data such as Landsat (with a 30 m spatial resolution). For a pixel to be defined as *Sargassum* using indices such as NDVI and FAI, Hu, Hardy, and Hochberg (2015) reported that it should at least cover between 1.0% and 2.0% of the area. For that pixel to be differentiated from other floating objects and detected as *Sargassum*, it should cover between 20.0% and 30.0%.

342 The presence and location of Sargassum lines are in constant motion; therefore, collecting 343 field data to calibrate multispectral images for their detection is highly complex and costly. 344 However, the current approach supports training site selection using index composites as well as 345 the probability of each pixel of being classified as *Sargassum*. We used these by-products as an 346 input to obtain a quantitative criterion for the interpretation of the resulting classification and the 347 accuracy assessment. This methodological approach is the first to present metrics (overall 348 performance, omission error, commission index, Kappa, and Tau) of its accuracy to detect 349 Sargassum using L8 images, thereby providing a baseline for comparing with other detection 350 methods.

In general, the values of all metrics indicated satisfactory performance, and it is worth noting the rate of omission errors (19.0%), which was highly relevant to this approach because *Sargassum* omissions were not corrected. Therefore, this value was directly estimated from the results of the classifier. The rate of this type of error was higher than that of the errors of commission (about 2.0%), which were corrected.

Regarding the Kappa and Tau metrics, Green et al. (2000) suggested acceptable accuracy values between 60.0% and 80.0% for handling and reference purposes; these values were fully realized in this study. In addition, these authors also expressed the need for greater accuracy when performing quantitative assessments such as a change detection analysis, for which they suggest values of approximately 90.0%.

361 Some areas that were not classified as *Sargassum* using our methodological approach 362 might have been omitted because the surface coverage of *Sargassum* within a pixel was minimal. 363 Thus, the spectral response did not reach the *Sargassum* detectability values and might have been 364 confused with another object in the image. In the supervision of the *Sargassum* classification

directly derived from the classification process, the areas suspected of presence were not added,thereby underestimating the area covered.

In terms of the general errors of omission, when using Landsat images, Hu, Hardy, and Hochberg (2015) reported uncertainty values about 30.0% when estimating *Sargassum* coverage. This uncertainty value and a correction factor they applied were obtained for the northern Gulf of Mexico where the characteristics of the lines of *Sargassum* differed from those in the Caribbean. Therefore, it is not well established whether this factor can be accurately applied to our known underestimations; however, it represents a reference for studies using remote sensing to detect *Sargassum*.

374 The application of vegetation indices to detect floating *Sargassum* involved the inevitable 375 risk of detecting other floating objects that have a radiometric response in the same range of the 376 light spectrum (Hu, Hardy, and Hochberg 2015, Xing et al. 2017). In particular, spectral 377 confusion of Sargassum with Syringodium and bacteria of the genus Trichodesmium has been 378 reported. Other objects, which certain indices might detect in the same radiometric range as 379 Sargassum, correspond to floating litter. However, Hu, Hardy, and Hochberg (2015) 380 acknowledge that no large aggregations of litter have been reported in the Gulf of Mexico. 381 As mentioned above and recognized by Hu et al. (2016) and Wang and Hu (2016), it is 382 difficult to assert that all of the objects detected in this study correspond to Sargassum. 383 Considering the data in the available literature, however, this study shares the same theoretical 384 basis of the red edge in the reflectance of vegetation in the NIR, which has proven useful for the 385 detection of floating vegetation, including Sargassum. 386 Furthermore, considering that *Trichodesmium* bacteria strongly respond to the blue band 387 (Hu, Hardy, and Hochberg 2015) and that the indices generated from the red edge play a more

important role in classification than band 2 (blue), the contribution of this band is not so

389 dominant to suggest the significant expression of *Trichodesmium*, even when its importance is 390 relevant. Moreover, these bacteria are likely rare in this region; therefore, *Syringodium* is one of 391 the objects with the greatest probability of being confused with *Sargassum*.

392 However, these same authors reported a high reflectance of *Syringodium* in bands 2 and 5

393 of the Landsat images. Considering that the response of pixels detected as *Sargassum* in the

394 spectral window of the image derived from the ratio between bands 2 and 5 had lower average

values than the red-edge indices (i.e., FAI, NDVI, SAVI, and ARVI), it is assumed that most of

396 the pixels classified as *Sargassum* are in fact *Sargassum*.

In addition, the dates during 2015 in which the greatest amounts of floating objects assumed to be *Sargassum* were detected coincide with the arrival dates of these macroalgae along the coasts of the Mexican Caribbean as well as with the temporal patterns detected by Wang and Hu (2016) in the WCA. In this context, a high probability exists that most objects identified as *Sargassum* were correctly classified.

402 *Multi-index methodological approach*

403 Reported specialized image processing for Sargassum detection addresses several issues 404 regarding satellite image conditions, although they have great potential for automatization. Wang 405 and Hu (2016) implemented an effective procedure to detect Sargassum using MODIS images to 406 systematize the detection process for thousands of images. Their approach was highly effective 407 and has many applications and uses. However, it requires a level of technical specialization and 408 computer equipment that could be important constraining factors for researchers with limited 409 resources and decision makers who require access to simple and reliable evaluation strategies. 410 These groups have the greatest need for attainable approaches that enable the assessment of the 411 presence and distribution of lines of floating macroalgae in their study areas.

412	Given the need to know the spatial-temporal patterns and the origins of algal blooms, we
413	proposed an approach to detect Sargassum in a low cost, efficient and technologically viable
414	alternative that considers different indices that can detect floating vegetation. Because our
415	approach includes the use of well known, standardized, and effective informatics tools (e.g., a
416	machine learning family classifier; Akar and Güngör, 2012), it is more advantageous and
417	convenient. As with every supervised classification algorithm, the contribution of diverse inputs
418	constitutes one of the most robust aspects of the development of decision trees. Therefore, seven
419	different sources were used for Sargassum detection in contrast to a single source.
420	Several studies have sought to define threshold values for certain indices (NDVI, FAI,
421	NDVI, among others) to identify pelagic Sargassum (Hu 2009; Gower and King 2011; Gower,
422	Young, and King 2013; Hu, Hardy, and Hochberg 2015; Hu et al. 2016, Xing et al. 2017).
423	Nevertheless, several conditions such as fog, haze, and sun glint are present in the L8 images that
424	do not allow the direct optimal separability of Sargassum from the remaining objects in the
425	image; thus, this multi-index supervised classification was applied.
426	Most vegetation indices used in this approach have been tested for use to detect
427	Sargassum and other floating macroalgae (Hu 2009; Wang and Hu 2016; Xing and Hu 2016) and
428	are considered viable alternatives given the scarcity of hyperspectral products that decisively
429	resolve the radiometric confusion of Sargassum with other objects. In general, the indices
430	assessed in this study showed a narrower range of values in the Sargassum pixels than the bands
431	alone, which suggests that the indices more directly captured the objects assumed to be
432	Sargassum in the images.
433	The similarity of the index values between the classes was evident, as were the variations
434	in the conditions within each of the assessed scenes. In this sense, the proposed approach makes

435 use of the separability of all of the indices combined with the classification algorithm working in

436 a seven-dimensional space to address each situation represented by an image in a particular way437 (Figure 6).

Regarding the separability of the *Sargassum* class, the most important indices were NDVI
and SAVI, followed by band 2. Although the contribution of the latter to the classification of
objects other than *Sargassum* suggests that this element is not diagnostic *per se*, it can be used to
detect *Sargassum* in association with another band such as band 5.

The functionality of this methodological approach to detect pelagic *Sargassum* was corroborated along with the possibility of transference to and implementation in any other area of interest. Standard remote sensing as well as geographic information system applications and analyses were used, and they can be replicated using a wide range of spatial analysis software. This method further represents a consistent, accessible, and versatile alternative approach that can be adopted and implemented in other regions and by other groups.

The adopted methodological approach includes both automated stages and supervision conducted by operators. Moreover, relatively low cost tools are used to implement algorithms for image processing and classification. We sought a cost-effective balance in which the supervision added value to the final result. The cost is minimal given that a quantitative coverage can be obtained without efforts to digitize the *Sargassum* coverage, a task that can be arduous and is subject to human error. In addition, this supervision is aided by diagnostic tools; therefore, only a minimal level of experience is required to identify the objects in the images.

Users must be previously trained to correctly identify *Sargassum* in satellite images using color composites as a reference (Wang and Hu, 2016). Following our approach, index composites are incorporated into the identification task, enabling a clearer and more precise definition of the training sites and the supervision of results. White pixels indicate a high value for the three indices, thereby allowing a color spectrum to distinguish *Sargassum* from its context.

As Wang and Hu (2016) documented, the intervention of a *Sargassum* observation
operator constitutes an alternative to improve detection accuracy. Although this method implies
an additional cost, it might be significantly more cost-effective than manually digitizing *Sargassum* polygons (*e.g.*, Xing et al. 2017), thereby increasing the analytical capacity in terms
of the number of images.

465 In this study, personnel inexperienced with satellite image analysis were successfully 466 trained to define the training sites. With the help of false color composites, calculated indices, 467 and probabilities obtained using the classification algorithm, the polygons erroneously assigned 468 as Sargassum by the classifier were identified and eliminated. The cost involved in this operation 469 was profitable in terms of correcting and increasing the level of accuracy of the images with a 470 minimum time investment because false assignments were minimal and well identified. The 471 performance of the people trained to classify the images was verifiable through the accuracy 472 metrics of the images.

473 Conclusions

This approach and its associated results represent an alternative methodological frame for the systematic and transferable detection of *Sargassum*.

We found that combining vegetation indices in a classification process is a more robust way to detect *Sargassum* in L8 images than using a single index. In addition, although the levels of confusion between the object of interest, the *Sargassum*, and other objects such as clouds, cloud shadows, and sun glint constitute an important challenge, this approach proposes a semiautomated classification process that provides the user with a margin to adjust to the particular conditions of each image.

These results are the first such assessment of the southeastern part of the Gulf of Mexico and the Mexican Caribbean. This quantification represents a baseline reference and it provides a further understanding of *Sargassum* coverage and dynamics.

- Given the possibility that similar massive blooms of this macroalga will occur in the
 future, this method represents an easily transferable approach that will support the monitoring
 and management of coastal areas affected by anomalous events.
- 488 The present work assessed *Sargassum* lines in Mexican territorial waters from the Gulf of 489 Mexico to the Mexican Caribbean in 2014 and 2015; however, the approach used in this study is
- 490 applicable to any region or moment of interest for which L8 images are available.

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Figure 1. Study area located in the northeastern region of the Yucatan Peninsula, México (*a*).
Black-lined polygons delimit the assessed scenes, and in a red square the small area represented

653 in (*b*); (*b*) Sargassum driftlines are indicated by a black arrow, as seen in a color composition

(bands 5, 2, 1) from a satellite image from Path 18 Row 45, July 2015.

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Figure 2. The importance of each of the indices and bands used for the supervised classification
(Random Forest) of 54 Landsat images for all classes considered (*a*) and for the *Sargassum* class
(*b*). The importance of a variable for a random forest model is estimated by looking at how much
prediction error increases when the testing data for that variable is permuted while all others are
left unchanged (Liaw & Wiener, 2002).



Figure 3. (*a*) Distribution of the frequencies of probability values of being *Sargassum* for the pixels in the whole scene (black) as well as the values for the pixels classified as *Sargassum* by the algorithm (dark gray) and those correctly assigned as *Sargassum* and refined by supervision (light gray). (*b*) The central tendency and dispersion values are presented for the three sets of pixels analyzed. Pixels with a probability lower than 0.1% were removed.



Figure 4. Spatial distribution of *Sargassum* drifts (*Sargassum* spp.) in the northeastern region of
the Yucatan Peninsula, Mexico during 2014 and 2015. Each frame shows a four-month
composite of all of the *Sargassum* detected during the correspondent period. Year 2014 is on the
left side, and year 2015 is on the right side. (a) January to April, 2014; (b) May to August, 2014;
(c) September to December, 2014; (d) January to April, 2015; (e) May to August, 2015; (f)
September to December, 2015.For presentation purposes, the lines that delimit the polygons are
1-point thick.

Figure 5. Temporal pattern of the cumulative coverage of the *Sargassum* drift lines in the studyarea in 2014 and 2015. [Figure in grayscale]

Figure 6. A simplified 3D representation of the informational elements and multi-index criteria
provided for the classification algorithm (Random Forest) used in the proposed classification
approach, which maximizes the separability between classes.

1 able 1. Synthesis of the vegetation index calcult and the parameters used for the equation	686 Table 1. Synthesis of the vegetar	ion index calculi and the parameters	s used for the equations.
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Vegetation index	Equation	Parameter	Author
NDVI	NDVI = $(\rho_{\text{NIR}} - \rho_{\text{R}}) / (\rho_{\text{NIR}} + \rho_{\text{R}})$ Equation (1)	ρ = atmospherically corrected reflectance band; NIR: Near infra-red band, R: Red band; B: Blue band;	Guyot and Gu 1994
ARVI	ARVI = $(\rho_{\text{NIR}} - \rho_{\text{R,B}}) / (\rho_{\text{NIR}} + \rho_{\text{R,B}})$ Equation (2)		Kaufman and Tanré 1992
SAVI	SAVI = $[(\rho_{\text{NIR}} - \rho_{\text{R}}) / (\rho_{\text{NIR}} + \rho_{\text{R}} + L)] (1 + L)$ Equation (3)	L = 0.5, is the context-dependent adjustment factor, which in this case is assumed to be the marine water in which <i>Sargassum</i> floats	Huete 1988
EVI	EVI = G $(\rho_{\text{NIR}} - \rho_{\text{R}}) / (\rho_{\text{NIR}} + C_{1,\text{R}} - C_{2,\text{B}} + L)$ Equation (4)	<i>G</i> is a gain factor (2.5); $C_{1,R}$ (6.0) and $C_{2,B}$ (7.5) are the aerosol resistance coefficients.	USGS, 2017
FAI	$FAI = \rho_{rc,NIR} - \rho'_{rc,NIR} \text{Equation (5)}$ Where $\rho'_{rc,NIR} = \rho_{rc,R} + (\rho_{rc,SWIR} - \rho_{rc,R}) (\lambda_{NIR} - \lambda_R) / (\lambda_{SWIR} - \lambda_R)$ Equation (6)	$\rho'_{\rm rc,NIR}$ is the base reflectance in the NIR band derived from a linear interpolation between the red (R) and the short-wave infrared (SWIR).	Hu 2009
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- Table 2. Quantitative metrics used in this study (adapted from Anderson et al. 2003) (Green et al. 2000) and their values calculated for
- all of the validated images with objects classified as *Sargassum* in the study area (N = 17).

Metric	Equation	Parameter
Overall performance (correct	(a+d)/(a+b+c+d) Equation (7)	a = true positives;
classification rate)		b = false positives;
Omission error (false negative	c / (a + c) Equation (8)	
rate)		c = false negatives; and,
Commission index (false positive	b/(b+d) Equation (9)	d = true negatives.
rate)		
Kappa	$K = \frac{N \sum_{i=1}^{r} X_{i,i} - \sum_{i=1}^{r} (X_{i,i} + X_{+,i})}{N^2 - \sum_{i=1}^{r} (X_{i,i} - X_{+,i})} \text{Equation (10)}$	where r is the number of rows in the confusion matrix;
	$\Delta_{i=1}^{(\Lambda_{l}+\Lambda_{+},l)}$	$X_{i,i}$ is the number of observations in row <i>i</i> and column <i>i</i> ;
		$X_{i,+}$ y $X_{+,i}$ are the marginal totals of row <i>i</i> and column <i>i</i> ,
		respectively; and N is the total number of validation
		points.
Tau	$\tau = \frac{P_0 - P_r}{1 - P_r}$, where $P_r = (\frac{1}{N^2}) \sum_{i=1}^M n_i X_i$	where P_o is the global accuracy; <i>M</i> is the number of
	Equation (11)	classes; <i>i</i> is the i^{th} class; <i>N</i> is the total number of
		validation points; n_i is the total of row i; and X_i is the
		diagonal value of class i.

- Table 3. Confusion matrix developed from the points defined to quantitatively validate the
- 696 Sargassum classifications.

Classification	Visual Validation		
Semi-Automated	Sargassum	Non Sargassum	
Sargassum	392	42	434
Non Sargassum	92	1,514	1,606
	484	1,556	2,040